

## **Chapter 3. Kaplan-Meier Curve and NPMLE**

1. Identifiability: noninformative versus independent censoring
2. Nonparametric estimation: Nelson-Aalen and Kaplan-Meier estimators
3. Asymptotic theory

- Likelihood contribution

1. failure  $t_j$ :  $\Pr\{T = t_j\} = \Pr\{T \geq t_j\} - \Pr\{T > t_j\} = S(t_j-) - S(t_j)$
2. independent censoring  $t_{jl}$ :  $\Pr\{T > t_{jl}\} = S(t_{jl}), l = 1, \dots, m_j$
3. total likelihood

$$\mathcal{L}(S) = \prod_{j=0}^k \left\{ [S(t_j-) - S(t_j)]^{d_j} \prod_{l=1}^{m_j} S(t_{jl}) \right\}$$

- Nonparametric maximum likelihood estimation (NPMLE)

1. maximize  $\mathcal{L}(S)$  with respect to  $S$ :  $\hat{S} = \arg \max_S \mathcal{L}(S)$
2.  $\hat{S}(t)$  has to be discontinuous at  $t_j$ ; otherwise  $S(t_j) - S(t_j-) = 0$
3.  $t_{jl} \geq t_j, S(t_{jl}) \leq S(t_j) \Rightarrow \max \hat{S}(t_{jl}) = \hat{S}(t_j)$
4.  $\hat{S}$  should be a step function with jumps at  $t_j$

- How to choose jump sizes to maximize  $\mathcal{L}(S)$ ?

1.

$$\begin{aligned}
 S(t_j) &= \Pr\{T > t_j\} = \Pr\{T \geq t_{j+1}\} \\
 &= \frac{\Pr\{T \geq t_{j+1}\}}{\Pr\{T \geq t_j\}} \cdot \frac{\Pr\{T \geq t_j\}}{\Pr\{T \geq t_{j-1}\}} \cdots \frac{\Pr\{T \geq t_2\}}{\Pr\{T \geq t_1\}} \cdot \Pr\{T \geq t_1\} \\
 &= \left[1 - \frac{\Pr\{T = t_j\}}{\Pr\{T \geq t_j\}}\right] \cdots \left[1 - \frac{\Pr\{T = t_1\}}{\Pr\{T \geq t_1\}}\right] \\
 &= \prod_{l=1}^j (1 - \lambda_l)
 \end{aligned}$$

2.  $S(t_j-) = \prod_{l=1}^{j-1} (1 - \lambda_l) \Rightarrow [S(t_j-) - S(t_j)]^{d_j} = \lambda_j^{d_j} \prod_{l=1}^{j-1} (1 - \lambda_l)^{d_j}$

3.

$$\mathcal{L}(S) = \prod_j^k \left[ \lambda_j^{d_j} \prod_{l=1}^{j-1} (1 - \lambda_l)^{d_j} \prod_{l=1}^j (1 - \lambda_l)^{m_j} \right] = \prod_j^k \lambda_j^{d_j} (1 - \lambda_j)^{n_j - d_j}$$

4.  $\hat{\lambda}_j = d_j/n_j \Rightarrow \hat{S}(t) = \prod_{t_j \leq t} (1 - d_j/n_j)$  is the NPMLE.

- Kaplan-Meier estimator

$$\hat{S}(t) = \prod_{t_j \leq t} \left(1 - \frac{d_j}{n_j}\right) \approx \prod_{t_j \leq t} e^{-\frac{d_j}{n_j}} = e^{-\sum_{t_j \leq t} \frac{d_j}{n_j}}$$

- Assume  $T$  is continuous  $\Rightarrow d_j = 1$  mostly

1.  $d_j = N(t_j) - N(t_j-) = dN(t_j)$

2.  $n_j = Y(t_j) > 0$

3.  $\sum_{t_j \leq t} \frac{d_j}{n_j} = \int_{u \leq t} I(Y(u) > 0) dN(u) / Y(u)$

- Nelson-Aalen estimator

$$\hat{\Lambda}(t) = -\log \hat{S}(t) = \int_0^t \frac{I(Y(u) > 0) dN(u)}{Y(u)}$$

### 3. Asymptotic theory

- Goals
  1. consistency: did we hit the target right?
  2. asymptotic distribution (normality): what is the error bound?
  3. efficiency: can we get the most of it?
- Nelson-Aalen estimator:  $\hat{\Lambda}(t) = \int_0^t I(Y(u) > 0) dN(u) / Y(u)$ 
  1. consistency
  2. asymptotically normal
  3. efficiency consideration

- What the Nelson-Aalen estimator estimates?
  - $E[dN_i(t) | \mathcal{F}_{t-}] = Y_i(t)\lambda(t)dt = Y_i(t)d\Lambda(t)$
  - $E[dN(t) | \mathcal{F}_{t-}] = Y(t)d\Lambda(t)$
  - $\hat{\Lambda}(t) = \int_0^t I(Y(u) > 0)dN(u)/Y(u) \simeq \int_0^t I(Y(u) > 0)d\Lambda(t) = \Lambda^*(t)$
- Asymptotic normality
  - $n^{1/2}[\hat{\Lambda}(t) - \Lambda^*(t)] \rightarrow \mathcal{N}(0, \sigma^2(t))$
- We will create a series of tools to establish the asymptotic properties

- Probability space  $(\Omega, \mathcal{F}, P)$ 
  - $\Omega = \{\omega\}$ : outcome space
  - $\mathcal{F}$ :  $\sigma$ -algebra; a collection of subsets of  $\Omega$ , satisfying the closure of complementation and countable unions; large-enough to contain most of the events to have reasonable probability measure
  - $P$ : probability measure, satisfying countably additivity  $P(\bigcup_i A_i) = \sum_i P(A_i)$  for disjoint  $A_i$ 's,  $P(\Omega) = 1$  and  $P(A) \geq 0$  for  $A \in \mathcal{F}$ .
  
- Random variable  $X : \Omega \mapsto R$ 
  - $X$  is  $\mathcal{F}$ -measurable if  $\{\omega : X(\omega) \leq x\} \in \mathcal{F}$  for any  $x$
  - distribution function:  $F(x) = P[\omega; X(\omega) \leq x]$
  
- Stochastic process  $\{X(t); t \in \Gamma\}$ 
  1. a collection of random variables indexed by  $t \in \Gamma$
  2. for a fixed  $\omega$ ,  $X(t; \omega)$  is a sample path as a function of  $t$

- Example: Brownian Motion  $X(t)$

- $X(t)$  are continuous in time  $t$
- for any set of  $t_1 < t_2 < \dots < t_k$ ,  $X(t_1)$ ,  $X(t_2) - X(t_1)$ ,  $\dots$ ,  $X(t_k) - X(t_{k-1})$  are independent normal random variables
- $\mu$ : drift;  $EX(t_1) = \mu t_1$ ,  $E[X(t_2) - X(t_1)] = \mu(t_2 - t_1)$ ,  $\dots$ ,  $E[X(t_k) - X(t_{k-1})] = \mu(t_k - t_{k-1})$
- $\sigma^2$ : diffusion;  $\text{var}[X(t_1)] = \sigma^2 t_1$ ,  $\text{var}[X(t_2) - X(t_1)] = \sigma^2(t_2 - t_1)$ ,  $\dots$ ,  $\text{var}[X(t_k) - X(t_{k-1})] = \sigma^2(t_k - t_{k-1})$
- **standard Brownian motion**:  $\mu = 0$ ,  $\sigma = 1$
- **time-transformed Brownian motion**:  $\mu = 0$ ,  $\text{var}\{X(t)\} = \alpha(t)$

- Filtration  $\mathcal{F}_t$ 
  - a family of sub- $\sigma$ -algebra  $\{\mathcal{F}_t; t \geq 0\}$
  - increasing  $\mathcal{F}_s \subset \mathcal{F}_t$  for  $s \leq t$
  - $\mathcal{F}_{t-} = \sigma(\bigcup_n \mathcal{F}_{t-1/n}); \mathcal{F}_{t+} = \bigcap_n \mathcal{F}_{t+1/n}$
  - right-continuous filtration:  $\mathcal{F}_t = \mathcal{F}_{t+}$
  
- Histories
  1.  $\mathcal{F}_t = \sigma(\{X(s); s \leq t\})$ : information about  $X(\cdot)$  up to  $t$
  2.  $\{W(t); t \geq 0\}$  is adapted to  $\mathcal{F}_t$  if  $W(t)$  is  $\mathcal{F}_{t-}$ -measurable
  
- Counting processes  $N_i(t)$ 
  1. right-continuous, piecewise constant, jump size of +1
  2. coupled with  $Y_i(t)$

- Conditional expectation  $E(Y | X)$ 
  1.  $E(Y | X)$  is  $\sigma(X)$ –measurable
  2.  $E(Y | X) = E[Y | \sigma(X)]$
  3. average prediction of  $Y$  given all the information we have on  $X$
  4.  $EY = E_X[E_{Y|X}(Y | X)]$
- Martingales  $M(t)$ 
  1.  $M(t)$  adapted to filtration  $\mathcal{F}_t$
  2.  $E|M(t)| < \infty$
  3.  $E[M(t + s) | \mathcal{F}_t] = M(t) \Rightarrow E[M(t)] = 0$

- Example: Brownian motion

1.  $\mathcal{F}_t = \sigma\{X(u); 0 \leq u \leq t\}$

$$\begin{aligned} E[X(t+s) \mid \mathcal{F}_t] &= E[X(t+s) \mid X(u); 0 \leq u \leq t] \\ &= E[X(t) + (X(t+s) - X(t)) \mid X(u); 0 \leq u \leq t] \\ &= X(t) + E(X(t+s) - X(t)) = X(t) + \mu s \end{aligned}$$

2.  $\mu = 0$ : martingale (fair)
3.  $\mu > 0$ : submartingale (winning)
4.  $\mu < 0$ : supermartingale (losing)

- Predictable processes  $W(t)$ 
  1.  $W(t)$  is  $\mathcal{F}_{t-}$ -measurable
  2.  $E[W(t) | \mathcal{F}_{t-}] = W(t)$
  3. left-continuous process adapted to  $\mathcal{F}_t$  is predictable
  4. example: at-risk process  $E[Y(t) | \mathcal{F}_{t-}] = Y(t)$

### 3. Asymptotic theory

- Doob-Meyer Decomposition Theorem
  - If  $X(t)$  is an adapted, right-continuous, non-negative submartingale, then there exists a unique right-continuous, increasing, predictable process  $A(t)$  such that  $A(0) = 0$ ,  $E[A(t)] < \infty$  and  $M(t) = X(t) - A(t)$  is a martingale
  - $dA(t) = E[dX(t) | \mathcal{F}_{t-}]$
- Example:  $N(t)$  is a submartingale
  - right-continuous, non-negative, increasing, finite expectation
  - $A(t)$ : compensator
  - $dA(t) = E[dN(t) | \mathcal{F}_{t-}]$
  - $A(t)$  depends on what  $\mathcal{F}_t$  is.

- Martingale:  $M(t)$ 
  - “time-dependent” residuals
  - variance:  $\text{var}\{M(t)\} = EM(t)^2$
- Variance:  $EM(t)^2$ 
  - $E[M(t+s)^2 | \mathcal{F}_t] \geq E[M(t+s) | \mathcal{F}_t]^2 = M(t)^2$ : submartingale
  - Doob-Meyer:  $M(t)^2 - \langle M, M \rangle (t)$  is martingale
 
$$d \langle M, M \rangle (t) = E[dM(t)^2 | \mathcal{F}_{t-}] = \text{var}\{dM(t) | \mathcal{F}_{t-}\}$$
  - predictable variation:  $\langle M, M \rangle (t)$ 

$$\text{var}\{M(t)\} = EM(t)^2 = \langle M, M \rangle (t)$$

- Example:  $M(t) = N(t) - \int_0^t Y(u)\lambda(u)du$

- $dM(t) = dN(t) - Y(t)\lambda(t)dt$

- 

$$\begin{aligned}
 \text{var}\{dM(t) \mid \mathcal{F}_{t-}\} &= \text{var}[dN(t) \mid \mathcal{F}_{t-}] \\
 &= E[dN(t)^2 \mid \mathcal{F}_{t-}] - E[dN(t) \mid \mathcal{F}_{t-}]^2 \\
 &= E[dN(t) \mid \mathcal{F}_{t-}] - E[dN(t) \mid \mathcal{F}_{t-}]^2 \\
 &= Y(t)\lambda(t)dt - Y(t)[\lambda(t)dt]^2 \\
 &= Y(t)\lambda(t)dt + o_p(dt)
 \end{aligned}$$

- $o_p(dt)/dt \rightarrow 0 \Rightarrow \int o_p(dt) \rightarrow 0$

- $d \langle M, M \rangle (t) = Y(t)\lambda(t)dt$

- Covariance:  $E[M_1(t)M_2(t)]$

- Predictable variation  $\langle M_1, M_2 \rangle (t)$

- \*  $M_1(t)M_2(t) - \langle M_1, M_2 \rangle (t)$  is martingale

- \*  $E[dM_1(t)M_2(t) \mid \mathcal{F}_{t-}] = d\langle M_1, M_2 \rangle (t)$

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$$\begin{aligned} d[M_1(t)M_2(t)] &= M_1(t)M_2(t) - M_1(t-)M_2(t-) \\ &= [M_1(t-) + dM_1(t)] \cdot [M_2(t-) + dM_2(t)] - M_1(t-)M_2(t-) \\ &= M_2(t-)dM_1(t) + M_1(t-)dM_2(t) + dM_1(t)dM_2(t) \end{aligned}$$

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$$\begin{aligned} E[d(M_1(t)M_2(t)) \mid \mathcal{F}_{t-}] &= E[dM_1(t)dM_2(t) \mid \mathcal{F}_{t-}] \\ &= \text{cov}[dM_1(t), dM_2(t) \mid \mathcal{F}_{t-}] \end{aligned}$$

- $\langle M_1, M_2 \rangle (t) = 0$ : orthogonal

- Example

- $M_1(t) = N_1(t) - \int_0^t Y_1(u)\lambda(u)du$

- $M_2(t) = N_2(t) - \int_0^t Y_2(u)\lambda(u)du$

- 

$$\begin{aligned}
 d \langle M_1, M_2 \rangle (t) &= \text{cov}[dM_1(t), dM_2(t) \mid \mathcal{F}_{t-}] \\
 &= E[(dN_1(t) - Y_1(t)\lambda(t)dt)(dN_2(t) - Y_2(t)\lambda(t)dt) \mid \mathcal{F}_{t-}] \\
 &= E[dN_1(t)dN_2(t) \mid \mathcal{F}_{t-}] - Y_1(t)\lambda(t)dt \cdot E[dN_2(t) \mid \mathcal{F}_{t-}] \\
 &\quad - E[dN_1(t) \mid \mathcal{F}_{t-}] \cdot Y_2(t)\lambda(t)dt + Y_1(t)Y_2(t)(\lambda(t)dt)^2 \\
 &= E[dN_1(t)dN_2(t) \mid \mathcal{F}_{t-}] - Y_1(t)Y_2(t)(\lambda(t)dt)^2 \\
 &= E[dN_1(t)dN_2(t) \mid \mathcal{F}_{t-}] + o_p(dt)
 \end{aligned}$$

- $E[dN_1(t)dN_2(t) \mid \mathcal{F}_{t-}] = 0$  as long as  $N_1(t)$  and  $N_2(t)$  don't always jump at the same  $t$

- Are we there yet?
  - Nelson-Aalen estimator

$$\begin{aligned}\widehat{\Lambda}(t) - \Lambda^*(t) &= \int_0^t \frac{I(Y(u) > 0)}{Y(u)} [dN(u) - Y(u)\lambda(u)du] \\ &= \sum_{i=1}^n \int_0^t \frac{I(Y(u) > 0)}{Y(u)} dM_i(u)\end{aligned}$$

- Parametric score function

$$\begin{aligned}l'(\theta) &= \sum_{i=1}^n \int_0^\infty [\log \lambda(u | Z_i; \theta)]'_\theta [dN_i(u) - Y_i(u)\lambda(u | Z_i; \theta)du] \\ &= \sum_{i=1}^n \int_0^\infty [\log \lambda(u | Z_i; \theta)]'_\theta dM_i(u)\end{aligned}$$

- what's (seemingly not) in common?
  1. yes:  $\sum$ ,  $\int$ ,  $dM_i(t)$
  2. seemingly not but yes: predictable intergrand

- $L(t) = \int_0^t H(u) dM(u)$ 
  - $M(t)$  is  $\mathcal{F}_t$ -martingale
  - $H(t)$  is  $\mathcal{F}_t$ -predictable
  - $L(t)$  is  $\mathcal{F}_t$ -martingale

- $\langle L, L \rangle (t)$ 
  - $L(t)^2$  is submartingale

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$$\begin{aligned} d \langle L, L \rangle (t) &= \text{var}[dL(t) \mid \mathcal{F}_{t-}] \\ &= \text{var}[H(t)dM(t) \mid \mathcal{F}_{t-}] \\ &= H(t)^2 d \langle M, M \rangle (t) \end{aligned}$$

- $\langle L_1, L_2 \rangle (t)$ 
  - $L_1(t)L_2(t)$  is submartingale

–

$$\begin{aligned} d \langle L_1, L_2 \rangle (t) &= \text{cov}[dL_1(t), dL_2(t) \mid \mathcal{F}_{t-}] \\ &= \text{cov}[H_1(t)dM_1(t), H_2(t)dM_2(t) \mid \mathcal{F}_{t-}] \\ &= H_1(t)H_2(t) d \langle M_1, M_2 \rangle (t) \end{aligned}$$

- Now it's time to study the asymptotics of

$$U_n(t) = \sum_{i=1}^n \int_0^t H_i(u) dM_i(u)$$

- Are we there yet?
  - Wait a second, what do we mean by asymptotics?
  - that means “what if sample size gets big...,” i.e.,  $n \rightarrow \infty$
  - what  $n$ , i.e., the order of  $n$ ?
  - $n^{-1}U_n$ ?  $n^{-1/2}U_n$ ?

- Mode of convergence:  $X_n \rightarrow X$

- convergence in probability  $X_n \rightarrow_P X$ : for any  $\epsilon > 0$

$$\Pr\{\omega : |X_n(\omega) - X(\omega)| > \epsilon\} \rightarrow 0$$

- almost surely  $X_n \rightarrow X, a.s.:$

$$\Pr\{\omega : \lim_{n \rightarrow \infty} X_n(\omega) = X(\omega)\} = 1$$

- convergence in distribution  $X_n \rightarrow_{\mathcal{D}} X$

$$\Pr\{\omega : X_n(\omega) \leq x\} \rightarrow \Pr\{\omega : X(\omega) \leq x\}$$

at continuity points of  $F_X(x)$

- Alternative view on convergence in distribution
  - any  $F_n(\cdot)$  defines a measure:  $\mathcal{P}_n = \mathcal{P}_{F_n}$
  - $\sigma\{(-\infty, x]; x \in R\}$  defines  $\mathcal{B}(R)$
  - $X_n \rightarrow_{\mathcal{D}} X \Leftrightarrow \mathcal{P}_n(B) \rightarrow \mathcal{P}(B)$  for any  $B \in \mathcal{B}$
  
- Weak convergence of stochastic processes
  - $\Gamma$ : metric space of  $X(\cdot)$
  - $\mathcal{S}_0$ :  $\sigma$ -algebra generated by all open sets
  - $\mathcal{P}_n(A) \rightarrow \mathcal{P}(A)$  for any  $A \in \mathcal{S}_0$

- Example

- $D[0, \tau]$ : cadlag functions

- $d(x, y)$ : Skorohod metric for  $x(t), y(t) \in D[0, \tau]$

- 1.  $r(\cdot)$ : strictly increasing time-transformation with  $r(0) = 0, r(\tau) = \tau$

- 2.  $d(x, y) = \inf\{\epsilon; \sup_t |x(t) - y[r(t)]| \leq \epsilon, \sup_t |r(t) - t| \leq \epsilon\}$

- 3. neighborhood:  $U(x; \delta) = \{y(t); d(x, y) < \delta\}$

- 4. open set  $A$ : for any  $x \in A$ , there exists  $U(x; \delta) \subset A$

- $\mathcal{S}$ :  $\sigma$ -algebra generated by all open sets

- $X_n(\cdot) \Rightarrow X(\cdot)$  iff  $\mathcal{P}_n(A) \rightarrow \mathcal{P}(A)$  for any  $A \in \mathcal{S}$

- Properties on weak convergence

1. Continuous mapping theorem: if  $X_n \Rightarrow X$ , then  $g(X_n) \rightarrow_{\mathcal{D}} g(X)$ ,

- $\sup_t \{X_n(t)\} \rightarrow_{\mathcal{D}} \sup_t \{X(t)\}$

- $(X_n(t_1), \dots, X_n(t_k)) \rightarrow_{\mathcal{D}} (X(t_1), \dots, X(t_k))$  for any  $(t_1, \dots, t_k)$

- $\int_0^T H(t) dX_n(t) \rightarrow_{\mathcal{D}} \int_0^T H(t) dX(t)$

2. Slutsky's theorem: if  $H_n \rightarrow_{\mathcal{D}} H$ , i.e.,  $\Pr\{\sup |H_n(t) - H(t)| > \epsilon\} \rightarrow 0$ :

- $H_n X_n \Rightarrow H X$

- $H_n + X_n \Rightarrow H + X$

- A theorem on weak convergence of cadlag processes

- $X_n$  and  $X$  are stochastic processes with cadlag sample paths on  $(D[0, \tau], \mathcal{S})$ , such that

- 1.  $(X_n(t_1), \dots, X_n(t_k)) \rightarrow_{\mathcal{D}} (X(t_1), \dots, X(t_k))$  for any  $(t_1, \dots, t_k)$

- 2.  $X_n$  is tight

- then  $X_n \Rightarrow X$  on  $(D[0, \tau], \mathcal{S})$

- Tightness

- $X_n$  is said to be tight, if there exists a compact set  $K$  such that  $\mathcal{P}_n(K) > 1 - \epsilon$  for any  $\epsilon > 0$ .

- Stone's sufficient condition: there exists  $d > 0$  such that for any  $\epsilon, \eta > 0$  and  $0 \leq s, t \leq \tau$

$$\limsup_{n \rightarrow \infty} \Pr\left\{ \sup_{|s-t| < d} |X_n(s) - X_n(t)| > \epsilon \right\} < \eta$$

- What is the asymptotic (limiting) distribution of

$$U_n(t) = \sum_{i=1}^n \int_0^t H_i(u) dM_i(u)$$

- Answer: Martingale Central Limit Theorem (MCLT)

- $U_n(t) \Rightarrow U$  on  $(D[0, \tau], \mathcal{S})$

- $U$  is a time-transformed Brownian motion

1.  $EU(t) = 0$

2.  $\text{var}\{U(t)\} = \lim_{n \rightarrow \infty} \langle U_n, U_n \rangle (t)$

3. independent increment:  $U(s)$  and  $U(t) - U(s)$  are independent for  $s \leq t$

- Assumptions

- convergent variance:  $\langle U_n, U_n \rangle (t) \rightarrow v(t)$

- smoothness (no spikes):  $\langle U_{n,\epsilon}, U_{n,\epsilon} \rangle (\tau) \rightarrow 0$  for any  $\epsilon > 0$ , where

$$U_{n,\epsilon}(t) = \sum_{i=1}^n \int_0^t H_i(u) I(|H_i(u)| \geq \epsilon) dM_i(u)$$

- Two more lemmata (Tsiatis, 1981):

1.  $Z_i$  are random variables such that  $Eg(Z_i)^2 < \infty$  where  $g(\cdot)$  is continuous, then

$$\sup_t \left| \sum_{i=1}^n \frac{g(Z_i)I(X_i \geq t)}{n} - E[g(Z)I(X \geq t)] \right| \rightarrow_P 0$$

2.  $Y_n(t) \rightarrow_P Y(t)$ ,  $Z_n(t) \rightarrow_P Z(t)$  and  $Q_n(t) \rightarrow_P Q(t)$ .  $Q_n(t)$  is positive and increasing.  $Q(\tau)$  is bounded.  $f(y, z)$  is continuous. Then

$$\sup_t \left| \sum_{i=1}^n \int_0^t f(Y_n, Z_n) dQ_n - \int_0^t f(Y, Z) dQ \right| \rightarrow_P 0$$

- Asymptotics of Nelson-Aalen estimator

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$$U_n(t) = \sqrt{n}[\hat{\Lambda}(t) - \Lambda(t)] = \sum_{i=1}^n \int_0^t \frac{\sqrt{n}}{Y(u)} dM_i(u)$$

for  $t < \tau = \sup_t \{t; \Pr(X \geq t) > 0\}$

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$$\begin{aligned} \langle U_n, U_n \rangle (t) &= \sum_i \int_0^t \frac{n}{Y(u)^2} Y_i(u) \lambda(u) du \\ &= \int_0^t \frac{n}{Y(u)^2} Y(u) \lambda(u) du \\ &= \int_0^t \frac{\lambda(u) du}{Y(u)/n} \longrightarrow v(t) = \int_0^t \frac{\lambda(u) dt}{EY_1(u)} \end{aligned}$$

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$$\begin{aligned} \langle U_{n,\epsilon}, U_{n,\epsilon} \rangle (t) &= \int_0^t \frac{n}{Y(u)} I \left( \frac{\sqrt{n}}{Y(u)} \geq \epsilon \right) \lambda(u) du \\ &= \int_0^t \frac{1}{Y(u)/n} I \left( \frac{n^{-1/2}}{Y(u)/n} \geq \epsilon \right) \lambda(u) du \longrightarrow 0 \end{aligned}$$

- Back-of-the-envelop calculations on

$$U_n(t) = \sum_{i=1}^n \int_0^t H_i(u) dM_i(u)$$

1.  $\text{cov}\{dM_i(t), dM_j(t) \mid \mathcal{F}_{t-}\} = 0$
2.  $\text{var}\{dM_i(t) \mid \mathcal{F}_{t-}\} = Y_i(t)\lambda(t)dt$

$$\int_0^t \sum_{i=1}^n H_i(u)^2 Y_i(u) \lambda(u) du \rightarrow v(t)$$